



Modeling of economic dynamics under stochastic noise:

Confidence domains in the analysis of noise-induced transition for Goodwin model

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Classical Goodwin model



$$\varepsilon\theta\ddot{Y}(t) + [\varepsilon + (1 - \alpha)\theta]\dot{Y}(t) - \varphi(\dot{Y}(t)) + (1 - \alpha)Y(t) = O^*(t) \quad [1]$$

where $Y(t)$ – income at time t ,
 ε – saving rate, $\varepsilon \in (0,1)$
 θ – the investment outlay

$$\ddot{Y}(t) + a \frac{Y^2(t) - 1}{Y^2(t) + 1} \dot{Y}(t) - bY(t) + cY^3(t) = O^*(t) \quad [2]$$

First question is: How did Lorenz and Nusse take this form of Goodwin model?

Second question is: How are new parameters a , b and c identified in terms of the parameters in classical model?

[1] R. Goodwin. The Nonlinear Accelerator and the Persistence of Business Cycles. // *Econometrica*, 19, 1 (1951), 1-17.

[2] H.W. Lorenz, H.E. Nusse. Chaotic attractors, chaotic saddles, and fractal basin boundaries: Goodwin's nonlinear accelerator model reconsidered. // *Chaos Solit. Fract.*, 13, (2002), 975-965



From Goodwin to van der Pol



$$\ddot{Y}(t) + \frac{\varepsilon + \theta[1 - c'(Y(t))]}{\varepsilon\theta} \dot{Y}(t) + \frac{Y(t) - c(Y(t))}{\varepsilon\theta} = \frac{\phi(Y(t), \dot{Y}(t))}{\varepsilon\theta} + \frac{\beta + \lambda - R}{\varepsilon\theta}$$

where β – autonomous consumption,

λ – autonomous investment,

$C(t)$ – consumption at time t ,

$\phi(t)$ – accelerator function at time t ,

R – the sum of the remainder terms for the respective Taylor expansions.

Assumption 1. $C(t) = \alpha Y + \gamma Y^3$, where $\alpha \in (0,1)$, $\gamma \in (-1,0)$

linear part

nonlinear term

Assumption 2. $\phi(Y(t), \dot{Y}(t)) = \psi(Y(t))\dot{Y}(t)$

$$\psi(Y) = \frac{\theta(1+Y^2)(1-\alpha-3\gamma Y^2)+2\varepsilon}{1+Y^2}$$

Interpretation: Instead of modeling the

accelerator as constant we allow the accelerator to vary in levels of income.

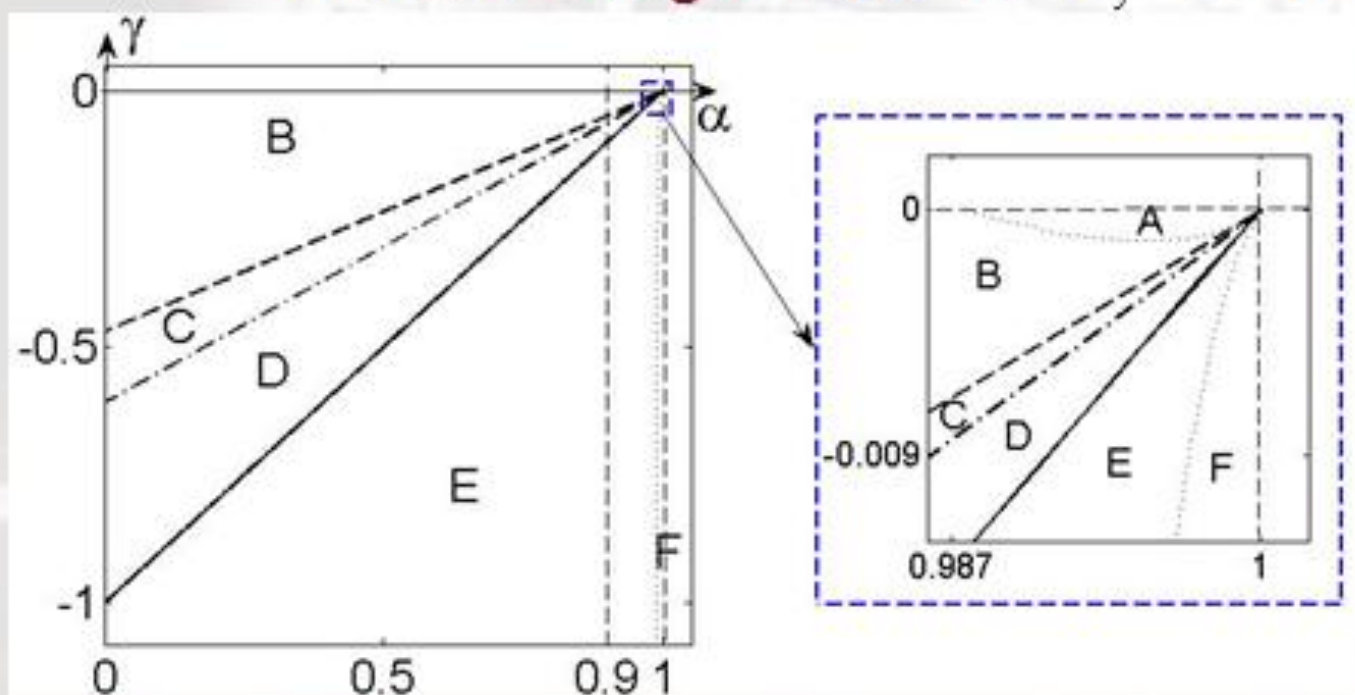
Deterministic attractors



$$\ddot{Y}(t) + \frac{1}{\theta} \cdot \frac{Y^2(t) - 1}{Y^2(t) + 1} \dot{Y}(t) - \frac{1 - \alpha}{\varepsilon \theta} Y(t) + \frac{-\gamma}{\varepsilon \theta} Y^3(t) = 0$$

3 equilibria $M_{1,2} = \left(\pm \sqrt{\frac{\alpha-1}{\gamma}}, 0 \right)$ and $M_3 = (0,0)$ M_3 – saddle

Bifurcation diagram for $\theta = 2$, $\varepsilon = 0.2$, for $M_{1,2}$



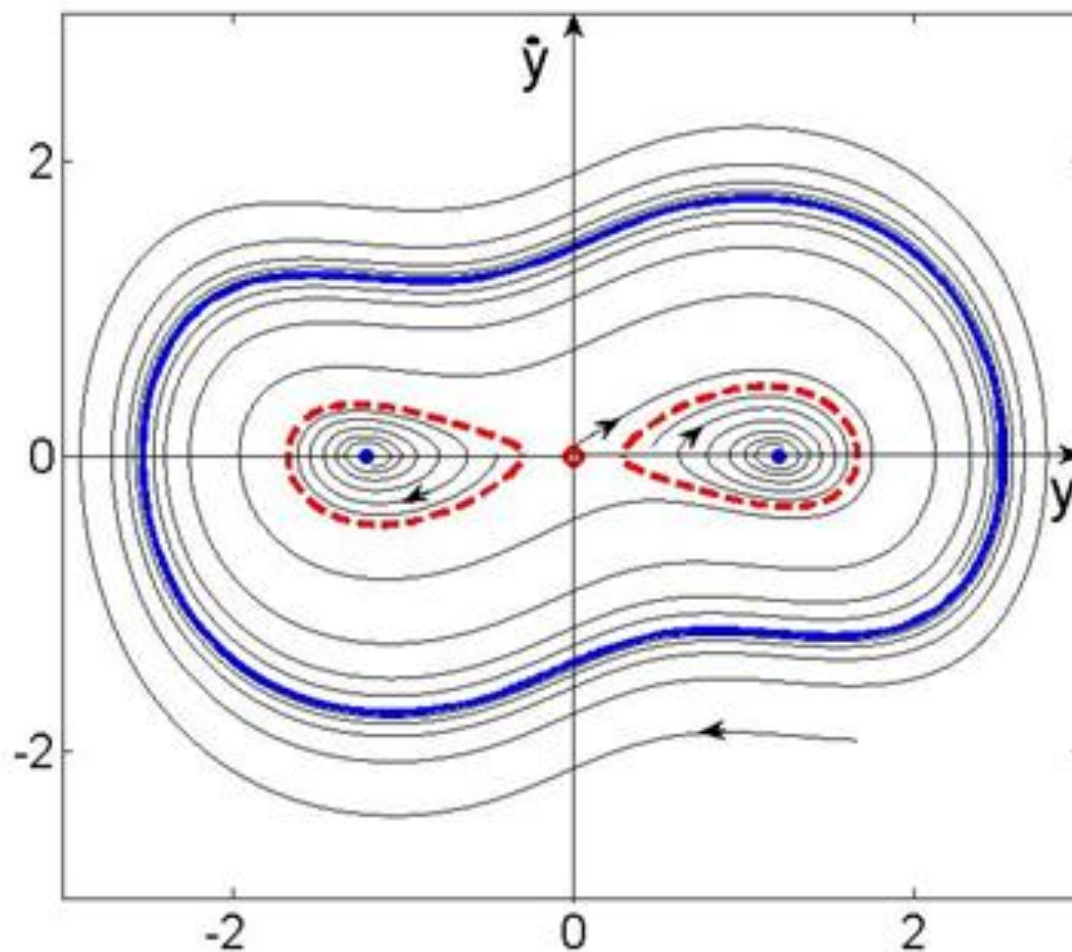
A – stable node,
 B }
 C } – stable focus,
 D }
 E – unstable focus,
 F – unstable node.

Numerically: C – one stable cycle and one unstable cycle,
 D – one stable cycle and two unstable cycle.

Deterministic attractors



Phase portrait for $\theta = 2$, $\varepsilon = 0.2$, $\alpha = 0.9$, $\gamma = -0.07$



Stochastic sensitivity function



$$\dot{x} = f(x) + \varepsilon \sigma(x) \dot{w}, \quad \text{- Ito equation}$$

$$\frac{\varepsilon^2}{2} \sum_{i,j=1}^n \frac{\partial^2}{\partial x_i \partial x_j} (a_{ij} \rho) - \sum_{i=1}^n \frac{\partial}{\partial x_i} (f_i \rho) = 0, \quad \text{Stationary Fokker-Planck equation}$$

$$a_{ij} = [\sigma \sigma^T]_{ij}$$

$$v(x) = - \lim_{\varepsilon \rightarrow 0} \varepsilon^2 \ln \rho(x, \varepsilon), \quad \text{- quasipotential [3]}$$

$$\rho(x, \varepsilon) \approx K \exp\left(-\frac{v(x)}{\varepsilon^2}\right) \quad \text{- asymptotic of the stationary distribution}$$

$$\text{Approximation quasipotential } v(x) \quad [4]$$

for equilibrium \bar{x}

$$v(x) \approx \frac{1}{2} (x - \bar{x}, W^{-1} (x - \bar{x}))$$

for T-periodic solution $x = \xi(t)$

$$v(x) \approx \frac{1}{2} (x - \xi(t), W^+(t) (x - \xi(t)))$$

[3] Freidlin M.I., Wentzell, A.D. Random Perturbations of Dynamical Systems. // Springer, New York (1984).

[4] I.A. Bashkirtseva, L.B. Ryashko Sensitivity and chaos control for the forced nonlinear oscillations. // *Chaos Solit. Fract.*, 26, 1437-1451 (2005).



Stochastic sensitivity function

I. Bashkirtseva, L. Ryashko [5]



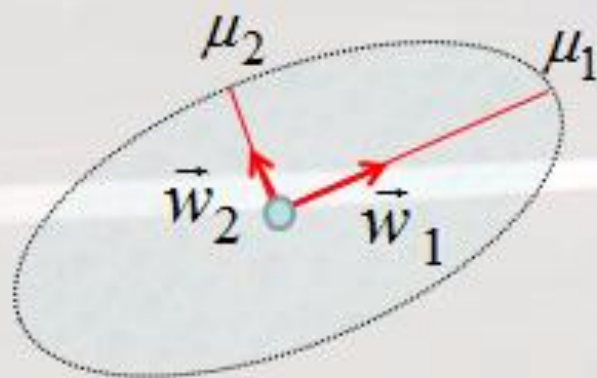
1. equilibrium

\bar{x} - an exponentially stable equilibrium

W - stochastic sensitivity matrix

$$FW + WF^T = -S,$$

where $F = \frac{\partial f}{\partial x}(\bar{x})$, $S = GG^T$, $G = \sigma(\bar{x})$.



\vec{w}_1, \vec{w}_2 - normalized eigenvectors of W

μ_1, μ_2 - eigenvalues of W

Stochastic sensitivity function

2. Limit cycle



$x = \xi(t)$ - an exponentially stable limit cycle corresponding T-periodic solution

$$\begin{cases} \dot{W} = F(t)W + WF^T(t) + P(t)S(t)P(t), \\ W(0) = W(T), \\ W(t)f(\xi(t)) \equiv 0, \end{cases}$$

where $F(t) = \frac{\partial f}{\partial x}(\xi(t))$, $S(t) = \sigma(\xi(t))\sigma^T(\xi(t))$,

$P(t)$ – a matrix of the orthogonal projection onto the hyperplane Π_t .

for 2d systems $W(t) = m(t)P(t)$, where $P(t) = p(t)p^T(t)$

$p(t)$ – a normalized vector orthogonal to $f(\xi(t))$,
 $m(t) > 0$ – a T - periodic scala function satisfying

$$\begin{cases} \dot{m} = a(t)m + b(t), \\ m(0) = m(T), \end{cases}$$

where $a(t) = p^T(t)(F^T(t) + F(t))p(t)$,
 $b(t) = p^T(t)S(t)p(t)$.

$m(t)$ - stochastic
sensitivity function
(SSF).

Stochastic Goodwin model



$$\ddot{Y}(t) + \frac{1}{\theta} \cdot \frac{Y^2(t) - 1}{Y^2(t) + 1} \dot{Y}(t) - \frac{1 - \alpha}{\varepsilon \theta} Y(t) + \frac{-\gamma}{\varepsilon \theta} Y^3(t) = \sigma \dot{w}$$

w – standart Wiener proces, σ – intensity of noise.

Stochastic sensitivity matrix for equilibrium

$$W = \begin{bmatrix} \mu_1 & 0 \\ 0 & \mu_2 \end{bmatrix},$$

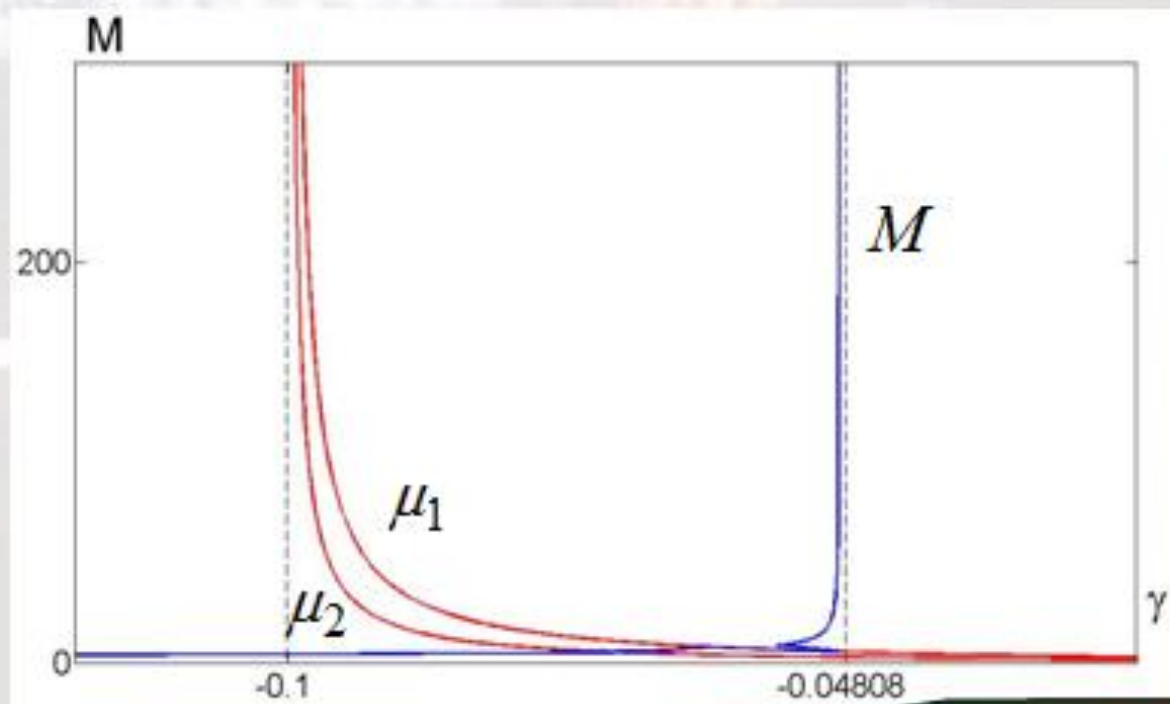
$$\mu_1 = \frac{\varepsilon \theta^2 (1 - \alpha - \gamma)}{4(1 - \alpha)(1 - \alpha + \gamma)},$$

$$\mu_2 = \frac{\theta(1 - \alpha - \gamma)}{2(1 - \alpha + \gamma)}$$

Stochastic factor for limit cycle

$$M = \max_{x \in [0, T]} m(t)$$

$$\begin{aligned} \theta &= 2, \\ \varepsilon &= 0.2, \\ \alpha &= 0.9 \end{aligned}$$

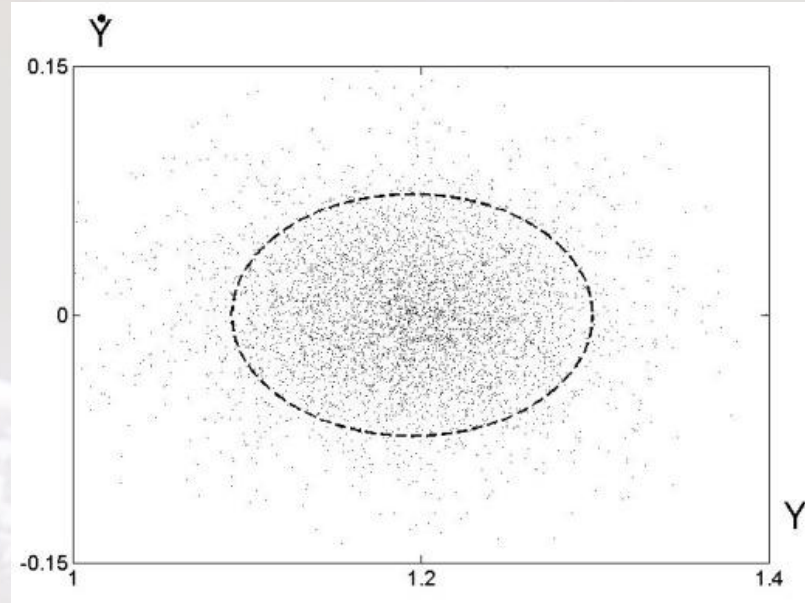


Stochastic Goodwin model



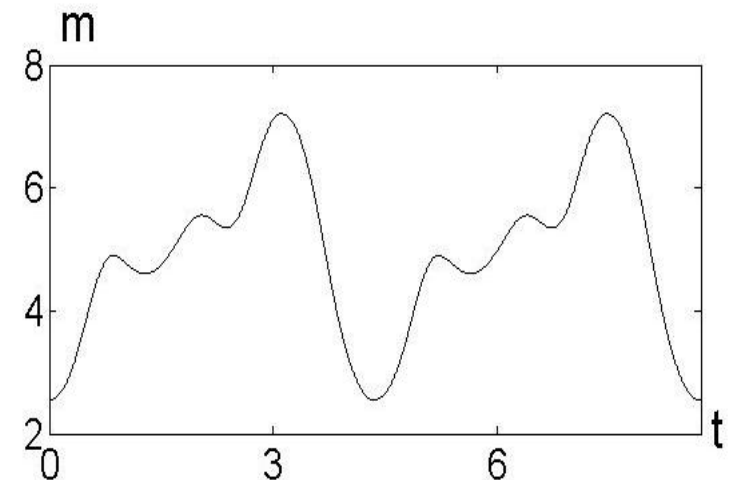
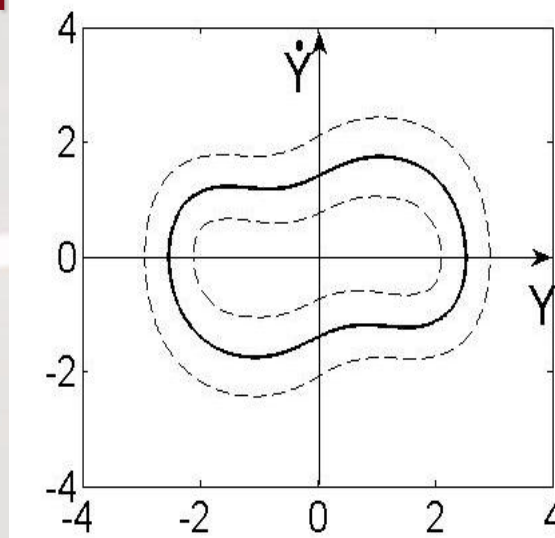
Confidence ellipse for
equilibrium

$$\theta = 2, \quad \varepsilon = 0.2, \quad \alpha = 0.9, \\ \gamma = -0.07, \quad \sigma = 0.01$$

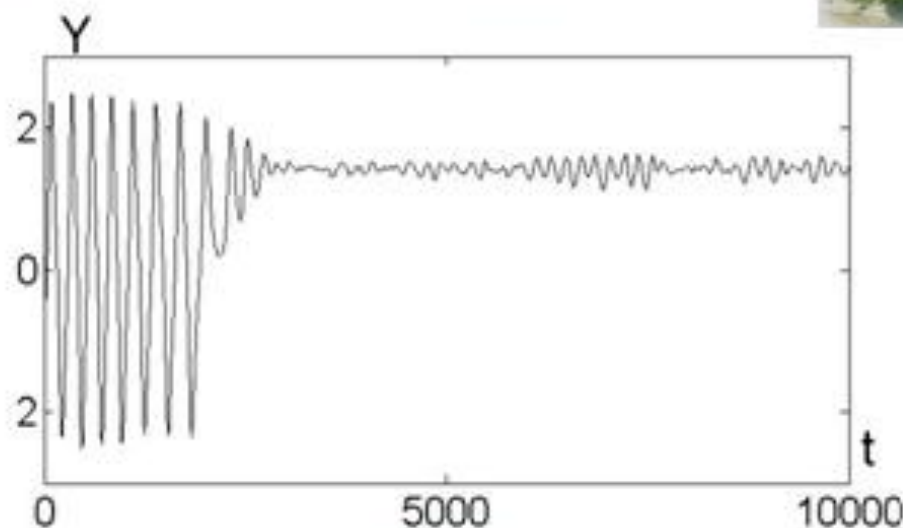
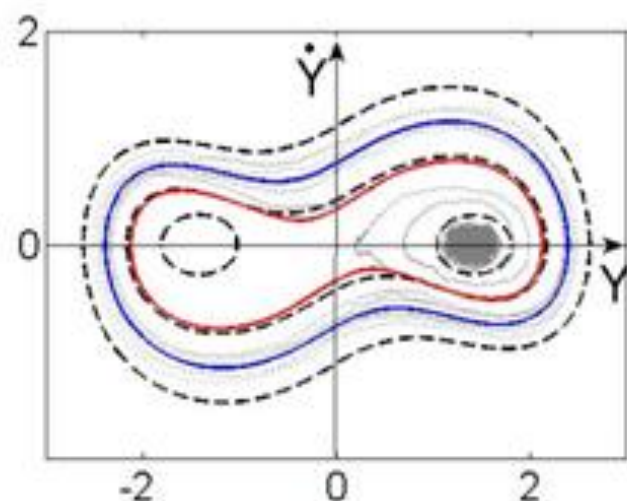


Confidence band for
limit cycle

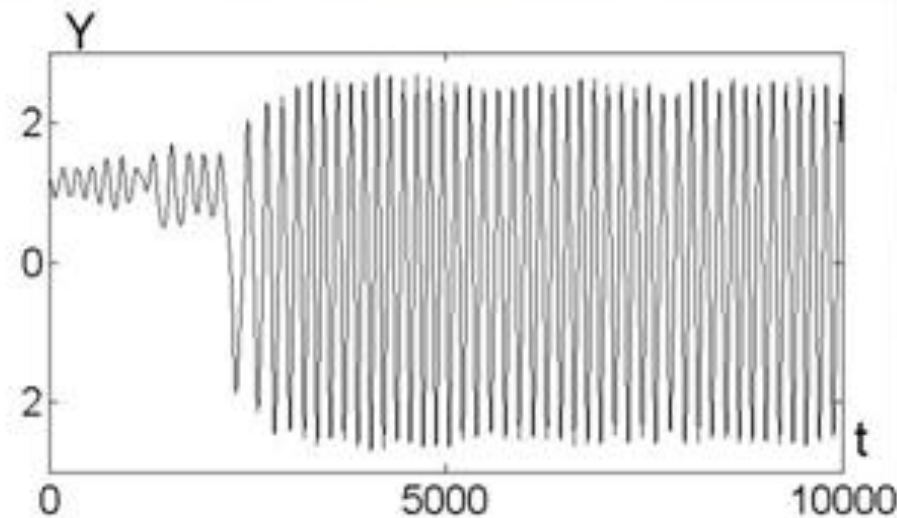
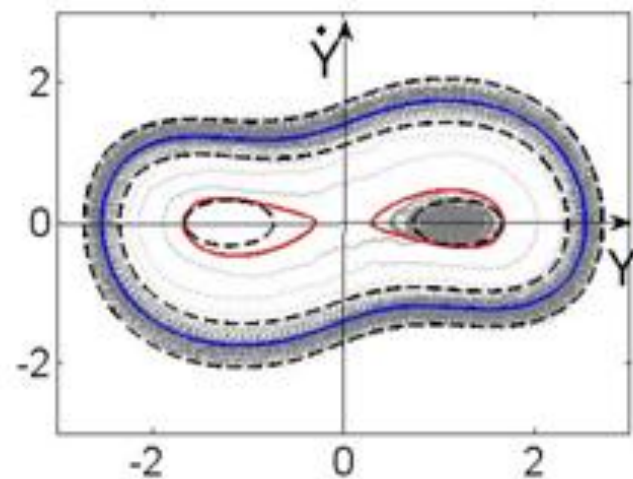
$$\theta = 2, \quad \varepsilon = 0.2, \\ \alpha = 0.9, \quad \gamma = -0.07 \\ \sigma = 0.1$$



Noise-induced transitions in Goodwin model



$$\theta = 2, \quad \varepsilon = 0.2, \quad \alpha = 0.9, \quad \gamma = -0.05, \quad \sigma = 0.03$$

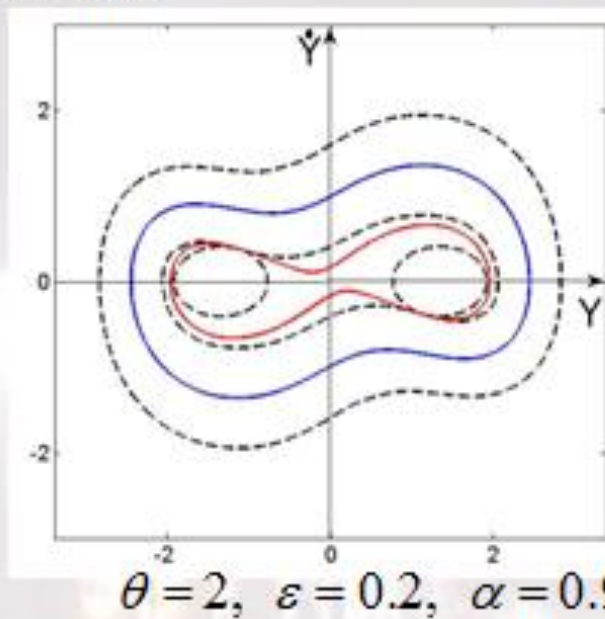
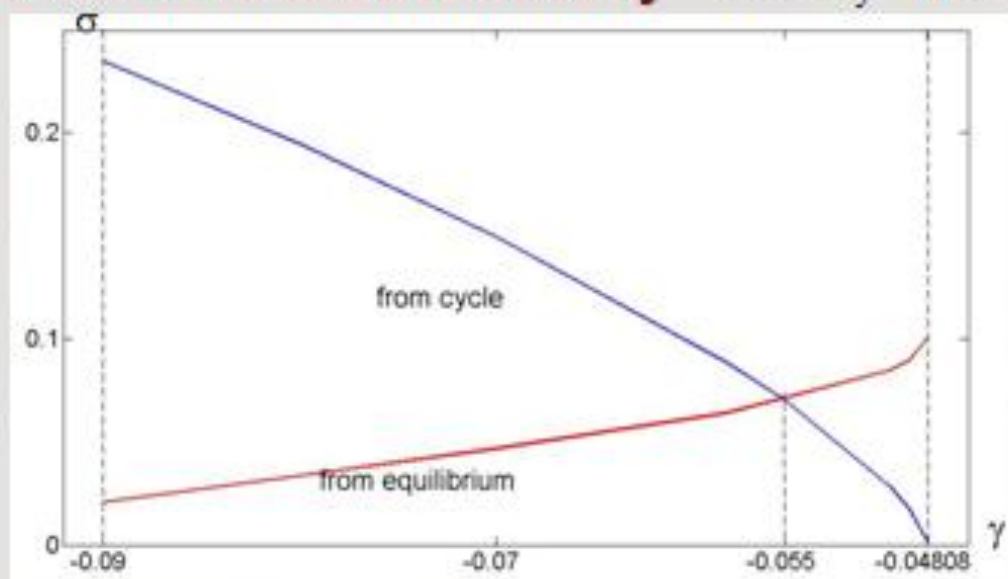


$$\theta = 2, \quad \varepsilon = 0.2, \quad \alpha = 0.9, \quad \gamma = -0.07, \quad \sigma = 0.045$$

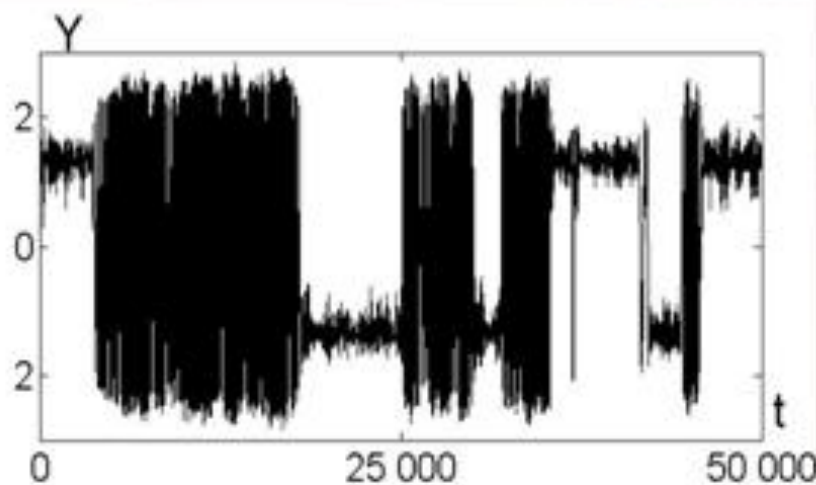
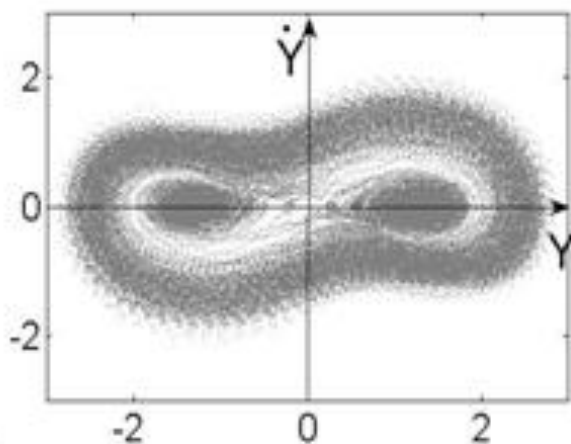
Noise-induced transition for Goodwin model



Critical values of intensity $\theta = 2, \alpha = 0.9, \varepsilon = 0.2$



$\theta = 2, \varepsilon = 0.2, \alpha = 0.9,$
 $\gamma = -0.055,$
 $\sigma = 0.07$



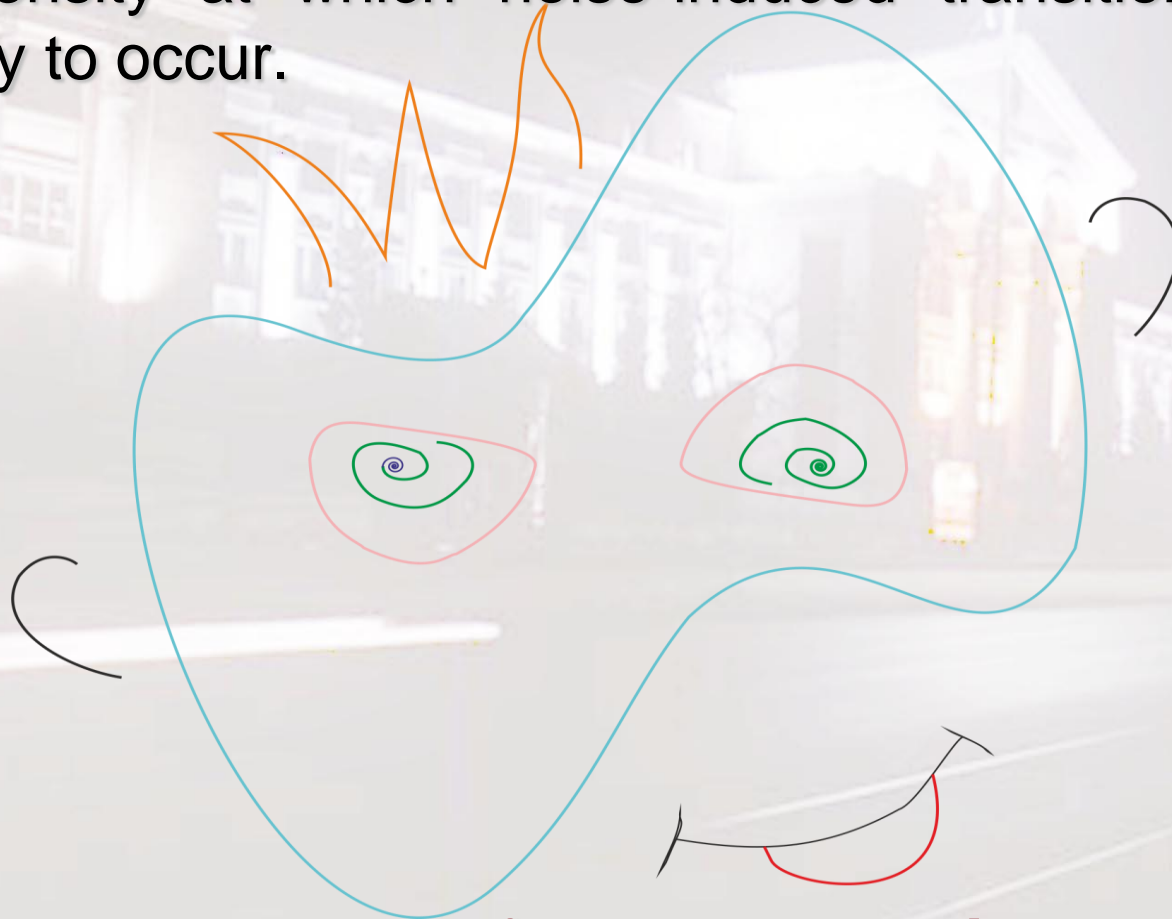
$\theta = 2, \varepsilon = 0.2, \alpha = 0.9, \gamma = -0.055, \sigma = 0.07$



Conclusion



We have demonstrated how the confidence domain method is used to understand the qualitative changes in stochastic dynamics and predict a critical value of the noise intensity at which noise-induced transitions are most likely to occur.



Thank you for your attention!