

# Growing Through Chaotic Intervals

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- description of the model;
- fixed points, 2-cycles, chaotic intervals; critical flip bif. and homoclinic bif.;
- classification of border-collision bifurcations.

## The growth model (Matsuyama, 1999)

Piecewise smooth unimodal map  $x_{t+1} = \phi(x_t)$ , where

$$\phi(x) = \begin{cases} f(x) = Gx^{1-1/\sigma}, & 0 < x < 1 \text{ (Solow regime)} \\ g(x) = \frac{Gx}{1+\theta(x-1)}, & x > 1 \text{ (Romer regime)} \end{cases}$$

$$\theta = (1 - 1/\sigma)^{1-\sigma}, \quad \sigma > 1.$$

$$x_t = K_t/N_t \sigma F \theta;$$

$K_t$  - capital;

$N_t$  - number of type of intermediate goods introduced up to time  $t$ ;

$F$  - some constant.

The output  $Y_t$  is related to  $K_t$  and  $N_s$ ,  $0 < s < t$ , through a production function.

A const. proportion of  $Y_t$  is left to be used as capital in the next period.

$\sigma$  denotes the demand elasticity of the intermediate good.

## Matsuyama, 1999:

- the model may have stable equilibria or unstable ones;
- the dynamics may oscillate alternatively between the Solow regime and the Romer regime, when there is a stable 2-cycle;
- the 2-cycle may lose its stability, leading to different dynamic behaviors, when the parameter  $G$  belongs to the range  $(1, (\theta - 1))$ ;
- complex dynamic behaviors may occur, although a 3-cycle cannot exist.

## Mitra, 2001:

- chaos may occur, at least when the parameter  $\sigma$  is quite high ( $\sigma = 50$ );
- The suf. cond.: the third iterate of the maximum is a point below the fixed point of the Romer regime (exactly the cond. for which the fix. p. has homoclinic trajectories).

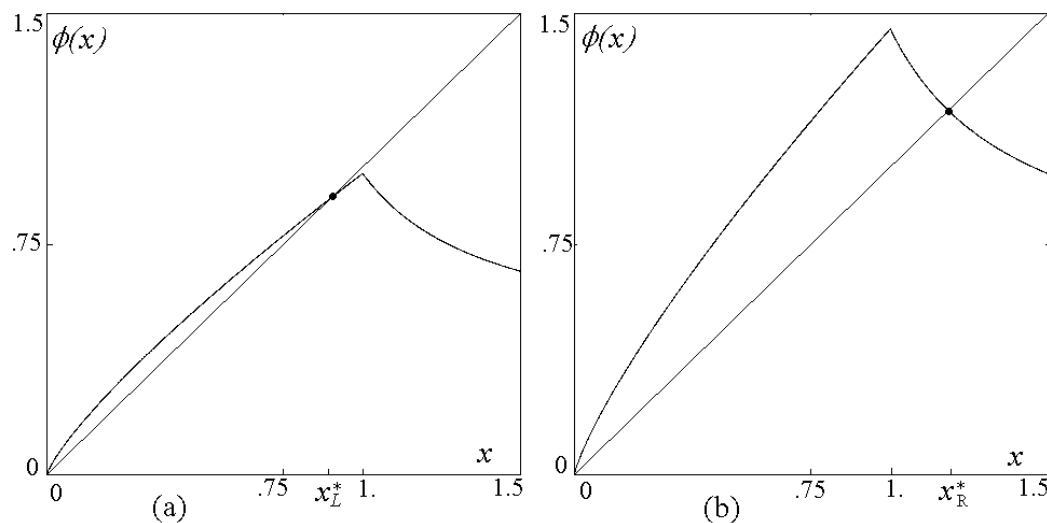
## Mukherjy, 2005:

- the cond. for chaos may be satisfied also at lower values of  $\sigma$ ,  $\sigma = 22$ ;
- the transition to chaos may occur via the per.-doubling bif. sequence (while this is not possible).

## Attracting fixed points, absorbing interval

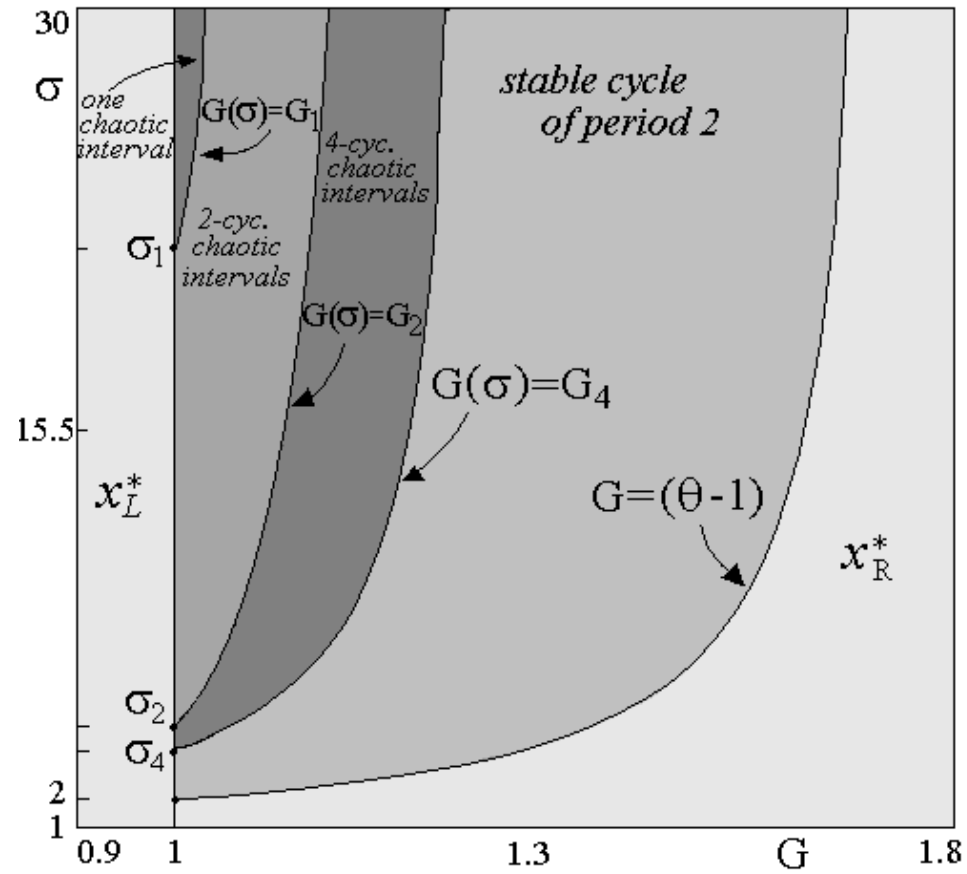
$f(x)$  has a unique fix. p.  $x_L^* = G^\sigma$  which exists ( $x < 1$ ) for  $G < 1$ , and when it exists, it is always globally attracting.

For  $G > (1 - \theta)$  the fix. p.  $x_R^* = 1 + \frac{G-1}{\theta}$  in the Romer regime is globally asymptotically stable ( $x > 1$ ).



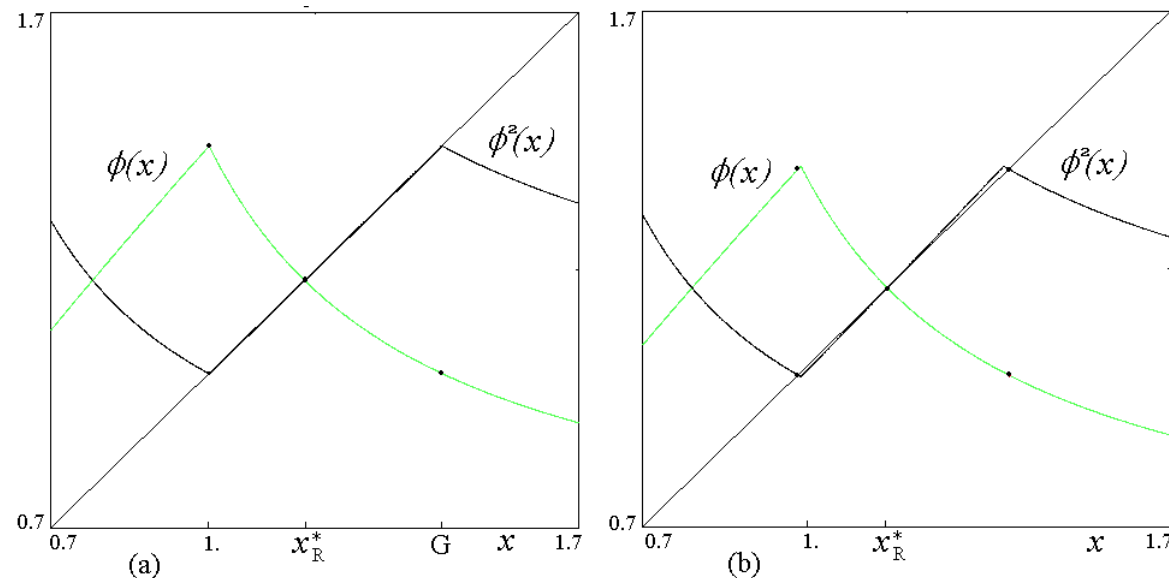
$\exists$  absorbing interval  $[g(G), G] : \phi([g(G), G]) \subseteq [g(G), G]$ .

## Two-dimensional bifurcation diagram in the $(G, \sigma)$ -parameter plane



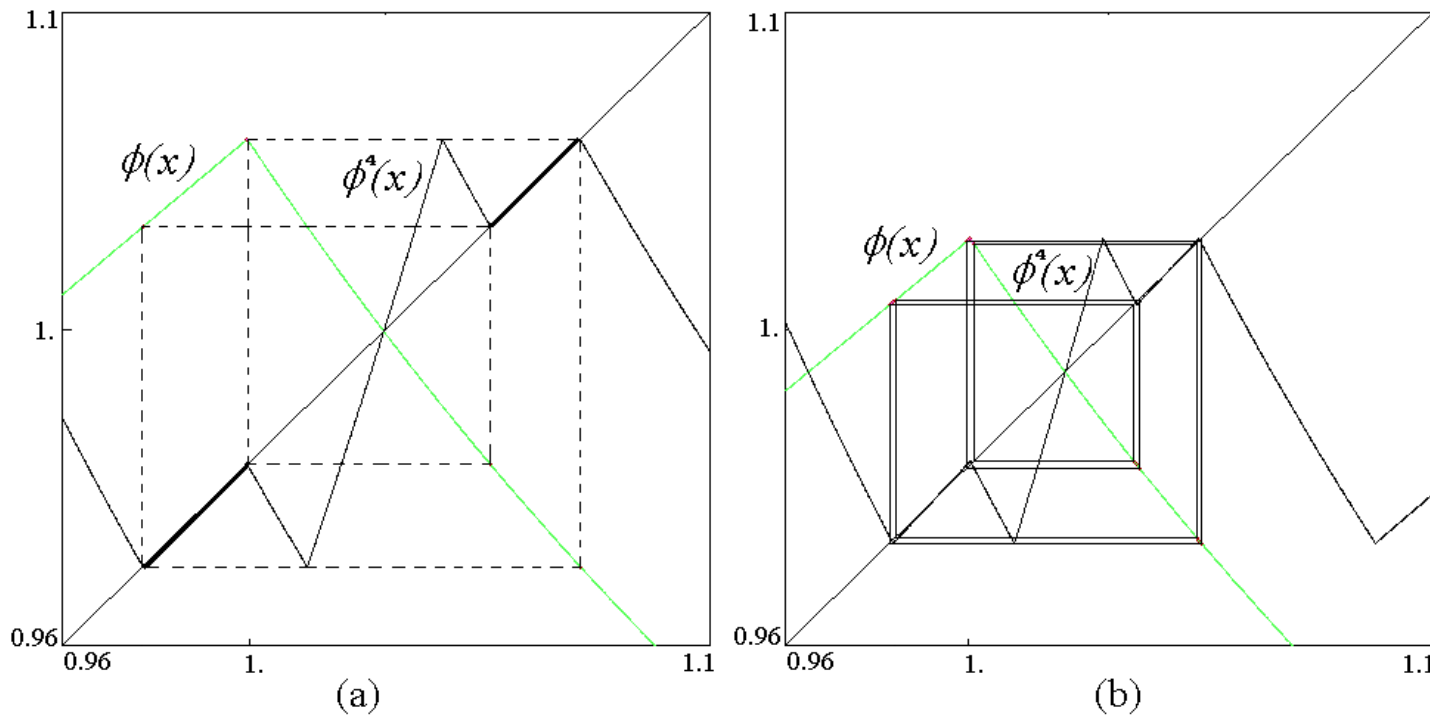
## Cycle of period 2

Let  $\sigma > 2$  be fixed and  $G$  decrease, starting from some  $G > (\theta - 1)$  for which  $x_R^*$  is stable. Then the loss of stability of  $x_R^*$  occurs via a critical bifurcation: At  $G = (\theta - 1)$  all the points of a segment are 2-cycles (in particular,  $\{1, G\}$ ).



A unique 2-cycle exists, after the bifurcation, for  $G < (\theta - 1)$ , say  $\{x_L, x_R\}$  :  $x_L < 1$  and  $x_R > 1$ .

The 2-cycle becomes unstable as  $G$  decreases reaching the value  $G = G_4$ .



**Proposition 1.** The stability region of the 2-cycle for any fixed value  $\sigma > 2$ , is bounded by the curves of implicit equations  $g^2(1) = 1$  (which corresponds explicitly to  $G = (\theta - 1)$ ) and  $g \circ f \circ g^2(1) = 1$  (implicit equation for  $G(\sigma) = G_4$ ).

## Chaotic intervals

Cycles of period three cannot exist, but the chaotic regimes exists anyhow. The sufficient condition stated by Mitra can be enforced in terms of homoclinic trajectories: (Devaney 1987, Gardini 1994):

**Proposition 2.** Let  $m$  be the unique critical point of a continuous piecewise smooth unimodal map of an interval into itself, say  $F : I \rightarrow I$ ,  $F(m)$  maximum (resp. minimum), with a unique unstable fixed point  $x^*$ , and a sequence of preimages of  $m$  tends to  $x^*$ . Then the first homoclinic orbits (all critical) of the fixed point  $x^*$  occur when the critical point satisfies  $F^3(m) = x^*$ . When the critical point is a local maximum (resp. minimum) then for  $F^3(m) < x^*$  (resp.  $F^3(m) > x^*$ ) infinitely many (noncritical) homoclinic orbits of the fixed point exist, and thus there is a closed invariant set  $X \subseteq [F^2(m), F(m)]$  (resp.  $X \subseteq [F(m), F^2(m)]$ ) on which the map is topologically conjugate to the shift automorphism, and thus  $F$  is chaotic, in the sense of topological chaos (with positive topological entropy).

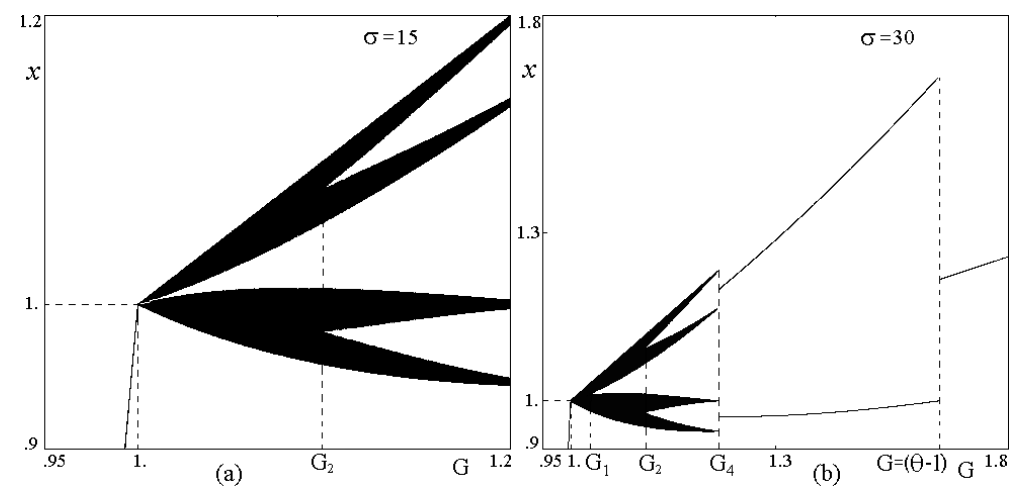
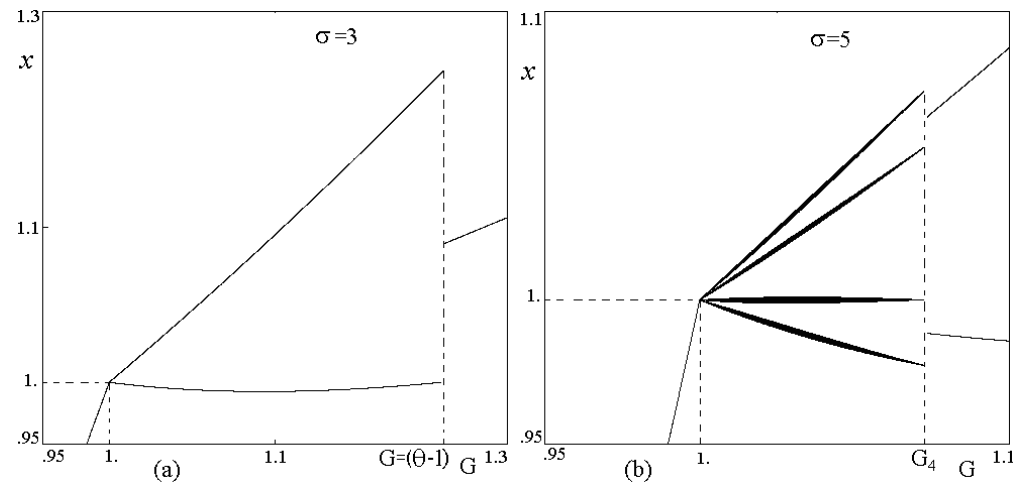


**Proposition 3.** For any fixed value  $\sigma > 2$  when the fixed point and the 2-cycle of the map are unstable, the attractors are full measure chaotic intervals.

The bifurcation  $I_4 \Rightarrow I_2$  is the homoclinic bifurcation of the repelling 2-cycle. The condition to detect this homoclinic bifurcation (Proposition 2 applied to  $\phi^2$ ) is  $\phi^5(1) = x_R$ , which corresponds to  $g^2 \circ f \circ g^2(1) = x_R$ .

The bifurcation  $I_2 \Rightarrow I_1$  occurs when the fix. p. in the Romer regime becomes homoclinic (by Proposition 2):  $\phi^3(1) = x_R^*$  that corresponds to  $f \circ g^2(1) = x_R^*$ , or more explicitly reads as follows:

$$G \left( \frac{G^2}{1 + \theta(G - 1)} \right)^{\left(1 - \frac{1}{\sigma}\right)} = 1 + \frac{G - 1}{\theta}.$$



## Border-collision bifurcation at $G = 1$

**Theorem.** The border-collision bifurcation of the fixed point  $x^* = 1$  of the map  $\phi$ , occurring at  $G = 1$  for any  $\sigma > 1$ , gives rise to

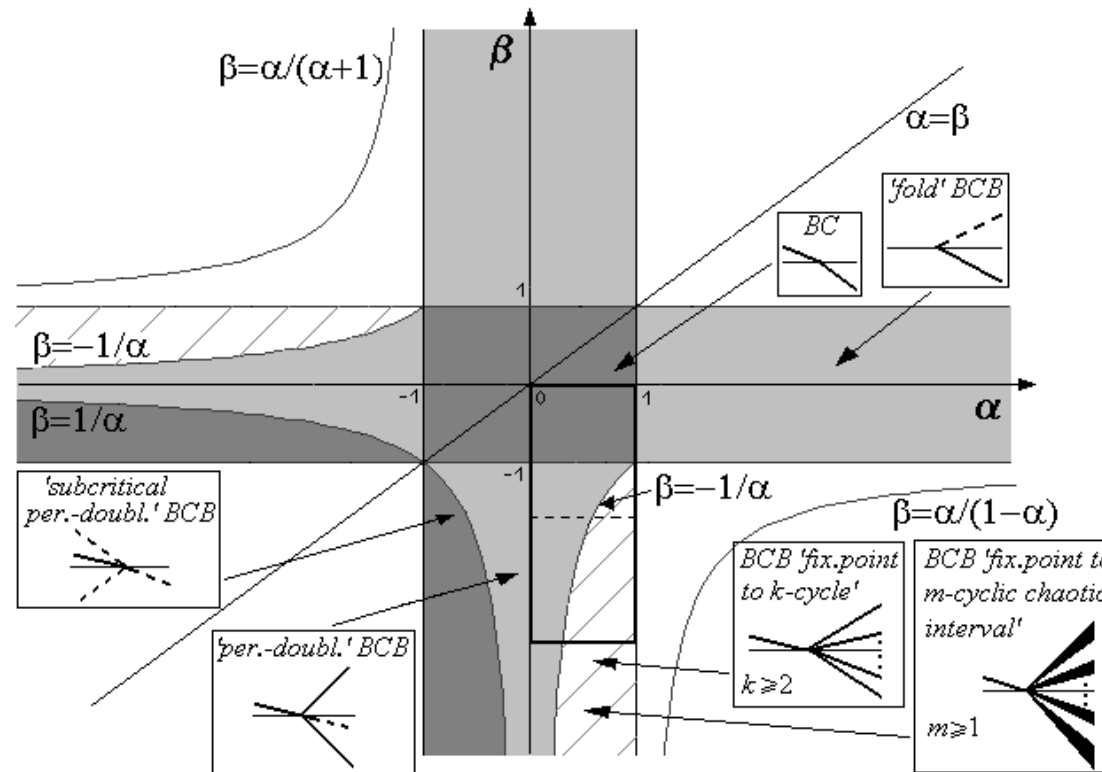
- an attracting fixed point  $x_R^*$  if  $1 < \sigma < 2$ ;
- an attracting cycle of period 2 if  $2 < \sigma < \sigma_4 \simeq 3.825$ ;
- attracting 4-cyclical chaotic intervals if  $\sigma_4 < \sigma < \sigma_2 \simeq 6.123$ ;
- attracting 2-cyclical chaotic intervals if  $\sigma_2 < \sigma < \sigma_1 \simeq 21.231$ ;
- an attracting chaotic interval if  $\sigma > \sigma_1$ .

Proof. The result of the border-collision bifurcation of the fixed point depends on the left and right side derivatives of  $\phi(x)$  evaluated at  $x = 1$  for  $G = 1$ , here denoted  $\alpha$  and  $\beta$ , respectively:

$$\alpha = \lim_{x \rightarrow 1^-} \frac{d}{dx} \phi(x), \quad \beta = \lim_{x \rightarrow 1^+} \frac{d}{dx} \phi(x).$$

The related normal form is given by the skew-tent map  $\psi : y \mapsto \psi(y)$  defined by the function

$$\psi(y) = \begin{cases} \alpha y + \varepsilon, & y \leq 0, \\ \beta y + \varepsilon, & y \geq 0. \end{cases}$$



The coefficients of the normal form in terms of the parameter  $\sigma$  :

$$\alpha = \left(1 - \frac{1}{\sigma}\right), \quad \beta = (1 - \theta), \quad (0 < \alpha < 1, \quad 1 - e < \beta < 0)$$

The border-collision curve  $B$  of  $x^* = 1$  in terms of  $\alpha$  and  $\beta$  :  $\beta = 1 - \alpha^{\alpha/(\alpha-1)}$ .



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